Quiz – Introduction to String Theory

Johanna Knapp

1. Commutator.

The commutator of two objects (you can assume that they are square $d \times d$ -matrices) is defined as [A, B] := AB - BA. Show that

- (a) [A, B] = -[B, A]
- (b) [A, B + C] = [A, B] + [A, C]
- (c) [AB, C] = A[B, C] + [A, C]B

We can also define an anticommutator: $\{A, B\} := AB + BA$. Decompose $\{AB, C\}$ like [AB, C] is decomposed above.

2. Euler-Lagrange equation.

Let x(t) be the position of a point-particle moving in one spatial dimension. Its motion is parameterised by a time coordinate t. Let $\dot{x} := \frac{dx}{dt}$. Given a "Lagrangian" $L = L(x, \dot{x})$ (x and \dot{x} are understood as independent variables), the equation of motion of the particle is given by the Euler-Lagrange equation

$$\frac{\partial L}{\partial x} - \frac{d}{dt} \frac{\partial L}{\partial \dot{x}} = 0. \tag{1}$$

Given $L = \frac{1}{2}\dot{x}^2$, compute the equation of motion and find the general solution. What is the physical interpretation of the equation and of its solution?

3. Conformal field.

Consider a "conformal primary field" $\phi(z)$ that has the following series expansion:

$$\phi(z) = \sum_{n = -\infty}^{\infty} \phi_n z^{-n-2}, \qquad z \in \mathbb{C}, \phi_n \in \mathbb{C}.$$
 (2)

Compute

$$\oint_C \phi(z)dz,\tag{3}$$

where C is a closed contour encircling z = 0.

Solutions

1. We verify this by explicit computation of both sides.

(a)

$$[A, B] = AB - BA$$

 $[B, A] = BA - AB = -(AB - BA)$ (4)

(b)

$$[A, B + C] = A(B + C) - (B + C)A = AB + AC - BA - CA$$
$$[A, B] + [A, C] = AB - BA + AC - CA$$
(5)

(c)

$$[AB, C] = ABC - CAB$$

$$A[B, C] + [A, C]B = A(BC - CB) + (AC - CA)B$$

$$= ABC - ACB + ACB - CAB = ABC - CAB.$$
 (6)

It is easy to show that the anticommutator is

$$\{AB, C\} = A\{B, C\} - \{A, C\}B.$$
 (7)

Let us verify this:

$$\{AB,C\} = ABC + CAB$$

$$A\{B,C\} - \{A,C\}B = A(BC + CB) - (AC + CA)B$$

$$= ABC + ACB - ACB + CAB = ABC + CAB$$
(8)

2. Since x and \dot{x} are independent we have

$$\frac{\partial L}{\partial x} = 0, \qquad \frac{\partial L}{\partial \dot{x}} = \dot{x}.$$
 (9)

The Euler-Lagrange equations are

$$0 - \frac{d}{dt}\dot{x} = -\ddot{x} = -\frac{d^2x}{dt^2} = 0 \quad \to \quad \ddot{x}(t) = 0. \tag{10}$$

This differential equation is easily solved by integration:

$$\dot{x}(t) = A, \qquad x(t) = At + B, \tag{11}$$

where $A, B \in \mathbb{R}$ are integration constants. The physical interpretation is as follows. If x(t) is the position of the particle at time t, \dot{x} is its velocity and \ddot{x} is the acceleration (i.e. change of velocity over time). The equation of motion describes a particle that is not accelerated and moves at a constant velocity A. Its position at t = 0 is x(0) = B.

3. The series expansion of $\phi(z)$ is a Laurent series with poles at z=0. Let us write down a few terms:

$$\phi(z) = \dots + \phi_1 z^{-3} + \phi_0 z^{-2} + \phi_{-1} z^{-1} + \phi_{-2} + \phi_{-3} z + \dots$$
 (12)

The integration contour encircles the poles at z=0, so the residue theorem tells us that

$$\oint_C \phi(z)dz = 2\pi i \operatorname{Res}_{z=0} \phi(z). \tag{13}$$

By definition, the residue is the coefficient of z^{-1} in the Laurent series expansion. Therefore we conclude

$$\oint_C \phi(z)dz = 2\pi i \phi_{-1}.\tag{14}$$